

On Privacy in Smart Metering Systems with Periodically Time-Varying Input Distribution

Yu Liu^a, Ashish Khisti^a, Aditya Mahajan^b

^a University of Toronto

^b McGill University

GlobalSIP Symposium on Privacy and Security

14 Nov, 2017

Smart Meters empower smart grids

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- ▶ Time-of-use pricing
- ▶ Demand response
- ▶ ...





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Comprehensive report: How smart meters invade privacy

August 29, 2014 by K. T. Weaver

big data, democracy, Fourth Amendment, privacy, rights, smart meters, spying

by K.T. Weaver, for Take Back Your Power

6 Comments

Last week, SkyVision Solutions released an updated **report** entitled, "A Perspective on How Smart Meters Invade Individual Privacy."





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Forbes / Tech

JUN 1, 2014 @ 01:15 PM 9,643 VIEWS

Doc By MATT **Smart Meters: Between Economic Benefits And Privacy Concerns**



Living

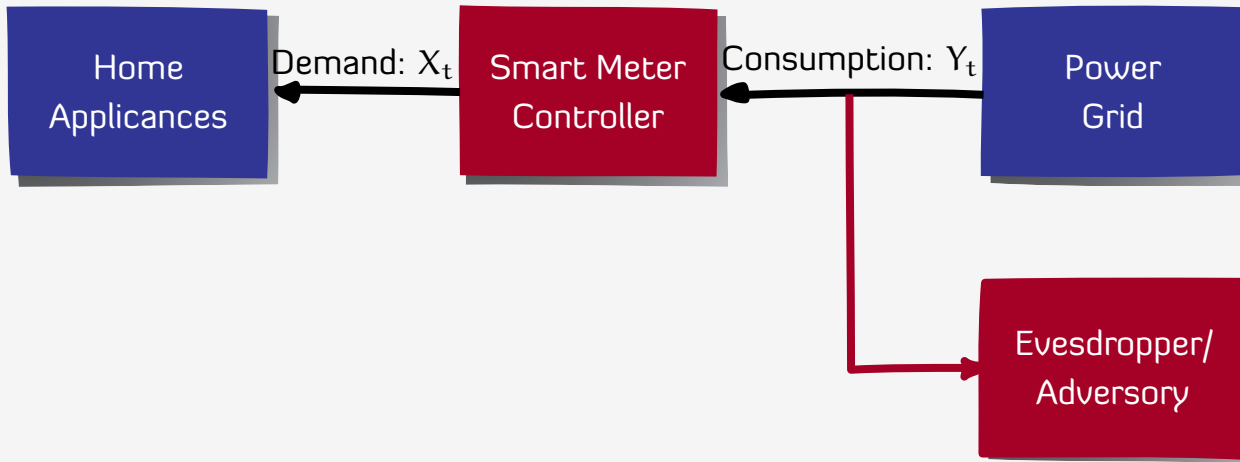
...future energy and health researchers get useful data from “smart meters”?

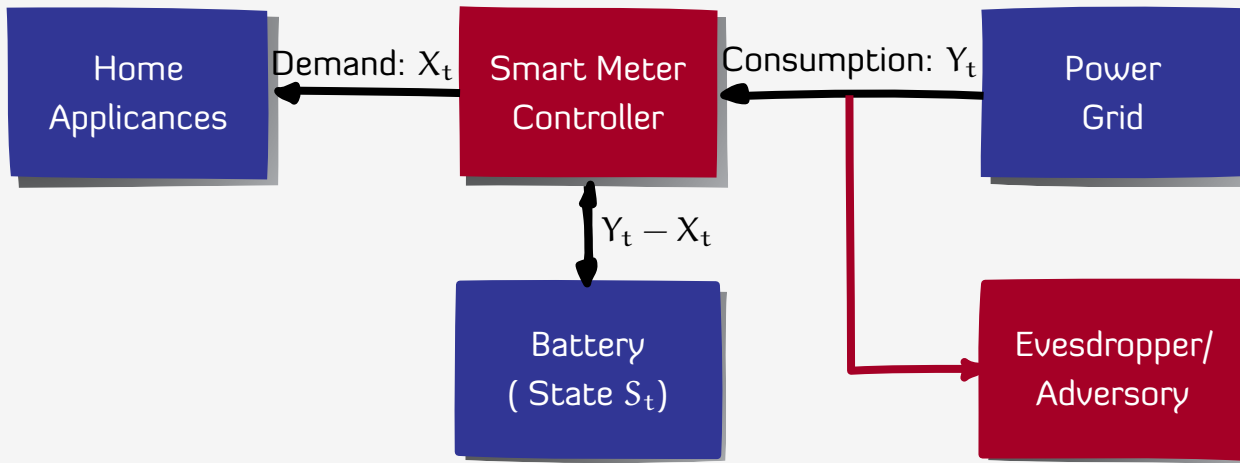
As utilities around the country install meters that can

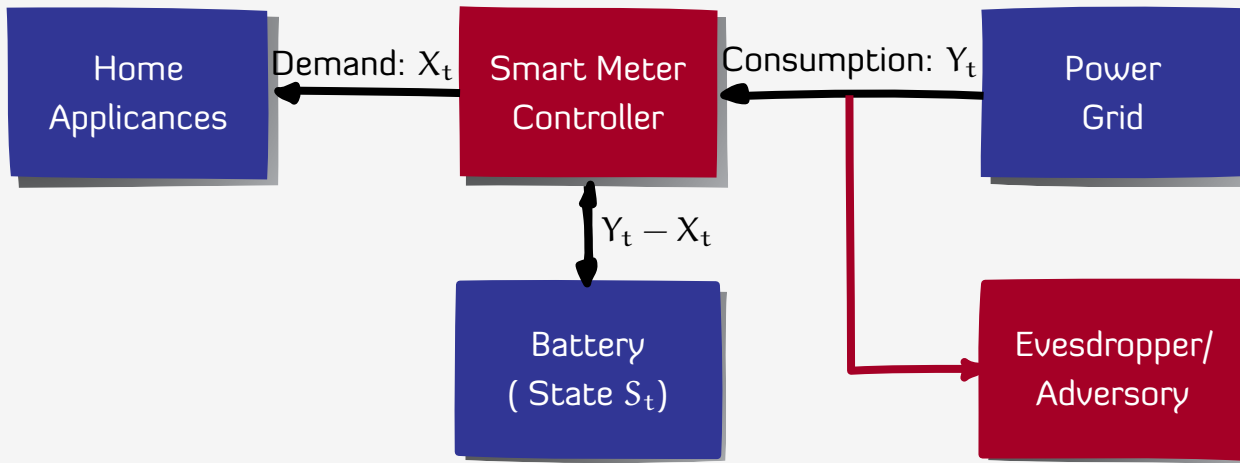
What is the minimum information leakage rate if consumers obfuscate consumption using a rechargeable battery?

What are privacy-optimal battery charging strategies?

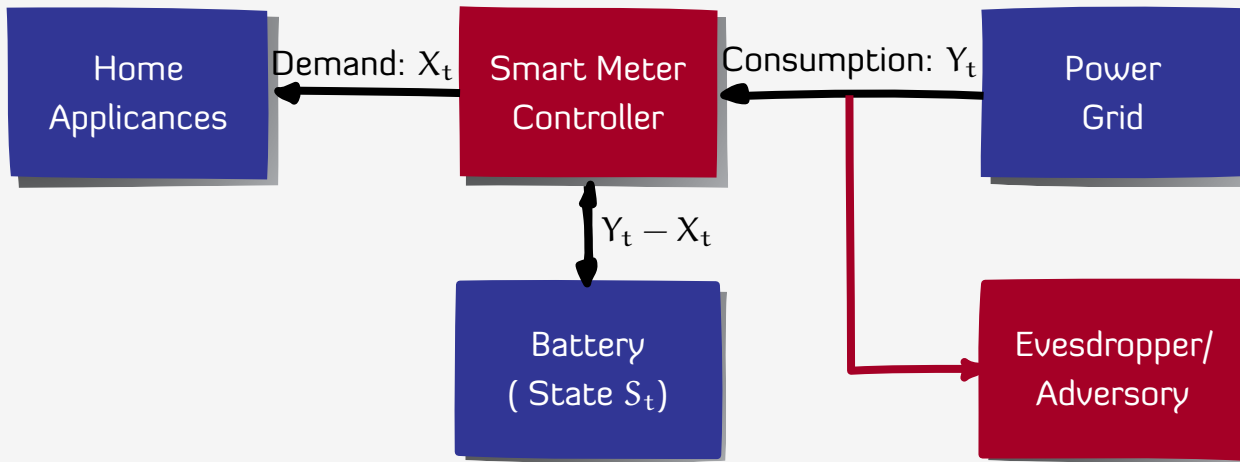






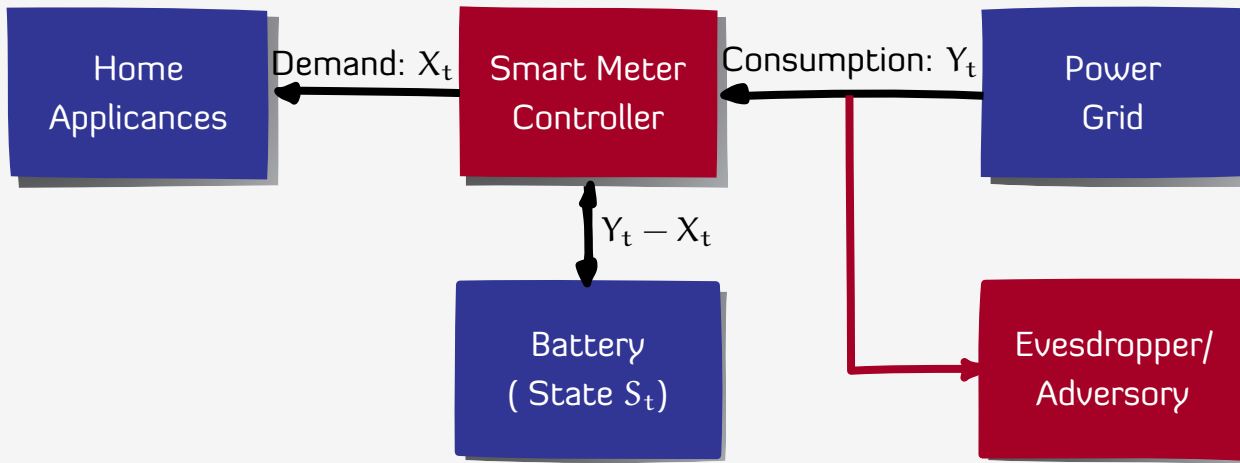


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Why is the problem non-trivial?

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Deterministic Memoryless Policy

- ▶ $P(Y|X = 0, S = 0) = [1 \ 0]$; $P(Y|X = 1, S = 1) = [0 \ 1]$: Leakage = 1 ($\because Y_t = X_t$).
- ▶ $P(Y|X = 0, S = 0) = [0 \ 1]$; $P(Y|X = 1, S = 1) = [1 \ 0]$: Leakage ≈ 1 ($\because Y_t = 1 - S_t$).

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Randomized Memoryless Policy

- ▶ $P(Y|X = 0, S = 0) = [0.5 \ 0.5]$; $P(Y|X = 1, S = 1) = [0.5 \ 0.5]$: Leakage = 0.5.
- ▶ Is this the **best** memoryless policy?
- ▶ Is this the **optimal** policy?
- ▶ How do we **evaluate** the performance of an arbitrary policy? Need $\mathbb{P}(X^T, Y^T)$?

Literature overview

Evaluate privacy of specific battery management policies

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- ▶ [Varodayan Khisti, 2011] Computing performance of **battery conditioned stochastic charging** policies using BCJR algorithm.
- ▶ [Tan Gündüz Poor, 2012] Generalized results of [Varodayan Khisti] to include models with energy harvesting.
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Dynamic programming decomposition to identify optimal policies

- ▶ [Yao Venkatasubramanian, 2013] Dynamic program, computable inner and upper bounds.
- ▶ Li Kshiti Mahajan, 2016 Dynamic program, closed form optimal strategy for i.i.d. case.

[LKM] Main results: Markovian demand

Structure of optimal strategies

- ▶ Define belief state $\pi_t(x, s) = \mathbb{P}(X_t = x, S_t = s | Y^{t-1})$
- ▶ Charging strategies of the form $q_t(y_t | x_t, s_t, \pi_t)$ are optimal.

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Dynamic programming decomposition

Let \mathcal{A} denote the class of conditional distributions on \mathcal{Y} given (X, S) .

Suppose there exists a $J \in \mathbb{R}$ and $v: \mathcal{P}_{X,S} \rightarrow \mathbb{R}$ that satisfies the following:

$$J^* + v(\pi) = \inf_{\mathbf{a} \in \mathcal{A}} \left\{ I(\mathbf{a}; \pi) + \sum_{x,s,y} \pi(x, s) \mathbf{a}(y|x, s) v(\varphi(\pi, y, \mathbf{a})) \right\}$$

Then,

- ▶ J^* is the minimum leakage rate
- ▶ Let $f^*(\pi)$ denote the arg min of the RHS and $\mathbf{a}^* = f^*(\pi)$.

Then, J^* is achieved by the charging policy

$$q^*(y|x_t, s_t, \pi_t) = \mathbf{a}^*(y|x_t, s_t) \quad (\text{note } \mathbf{a}^* \text{ depends on } \pi_t)$$

- ▶ Inspired by the approach used for capacity of Markov channels with feedback (Goldsmith Varaiya 1996, Tatikonda Mitter 2009, Permuter et al 2008)
- ▶ The DP is similar to the DP for POMDPs but the per-step cost is concave rather than linear.
- ▶ $v(\pi)$ is concave. So, computational approaches for POMDPs work.

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Solution of the dynamic program

$$J^* := \min_{\theta \in \mathcal{P}_S} I(S - X; X)$$

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[LKM] Salient features of the solution

$I(S - X; X)$ is concave in \mathcal{P}_S

J^* and θ^* may be computed using Blahut–Arimoto algorithm.

Optimal policy is stationary and memoryless

$q_t^*(y|x^t, s^t) = b^*(y|x_t, s_t)$ (note b^* does not depend on π_t)

If $S_t \sim \theta^*$, then $S_{t+1} \sim \theta^*$ and $S_{t+1} \perp Y^t$.

Support of consumptions

Even if $\mathcal{Y} \supset \mathcal{X}$, under the optimal policy the support of P_Y is \mathcal{X} .

This paper: Periodic Input Distribution

Periodic input $X_{\text{odd}} \sim Q_1(\cdot)$ and $X_{\text{even}} \sim Q_2(\cdot)$.

We assume that the input cycles between two distributions (each of length one). Results easily generalize to a larger cycle or staying at each distribution for a different amount of time.

Conceptual diff. Same as before. The leakage rate is a multi-letter mutual information expression that depends on $\mathbb{P}(X^T, Y^T)$.

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Solution idea We can use the qualitative properties of the i.i.d. solution to get achievable upper bounds. Compare them with non-achievable lower bounds.

Achievable scheme and lower bound

Achievable scheme Arbitrarily restrict attention to periodic policies:

- ▶ For odd time: $q_1(y_t|x_t, s_t)$
- ▶ For even time: $q_2(y_t|x_t, s_t)$

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This induces $\mathbb{P}(S_t) = P_{S_1}$ for odd times and P_{S_2} for even times.

$$L^* \leq L_\infty(\mathbf{q}) = \frac{1}{2}I(S_1, X_1; X_1) + \frac{1}{2}I(S_2, X_2; X_2).$$

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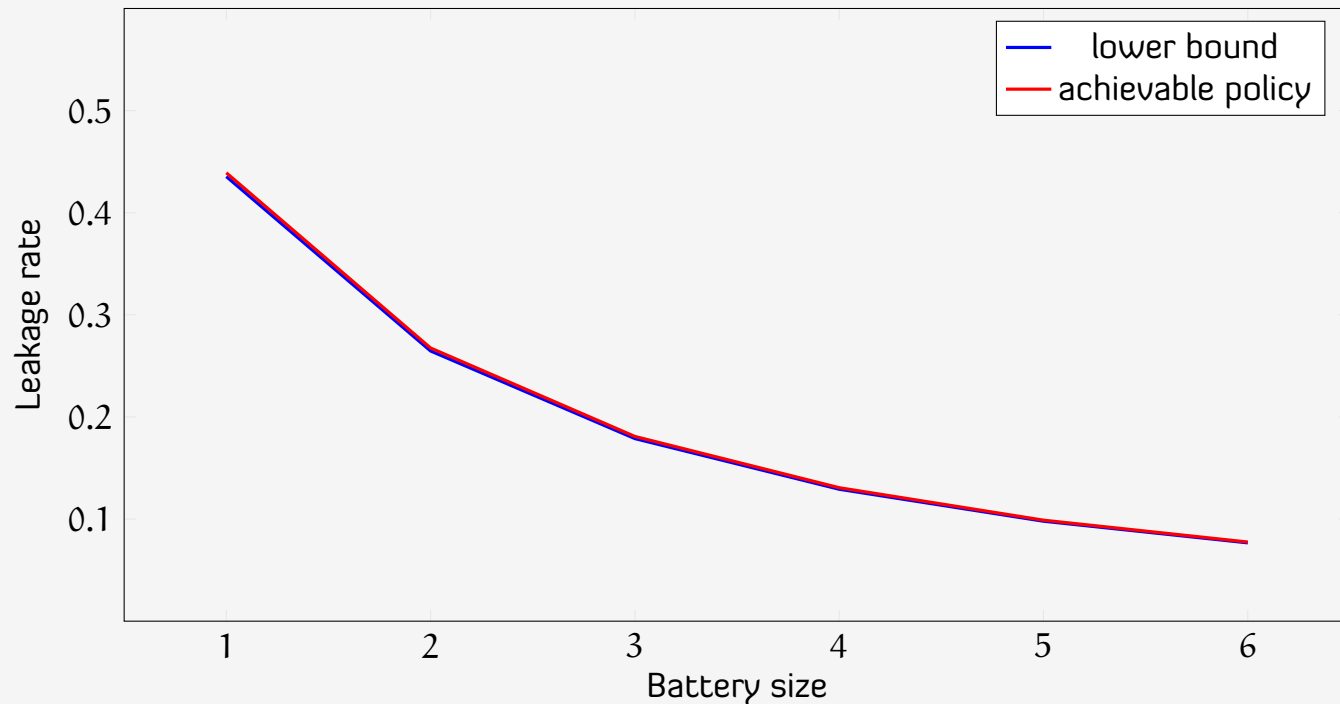
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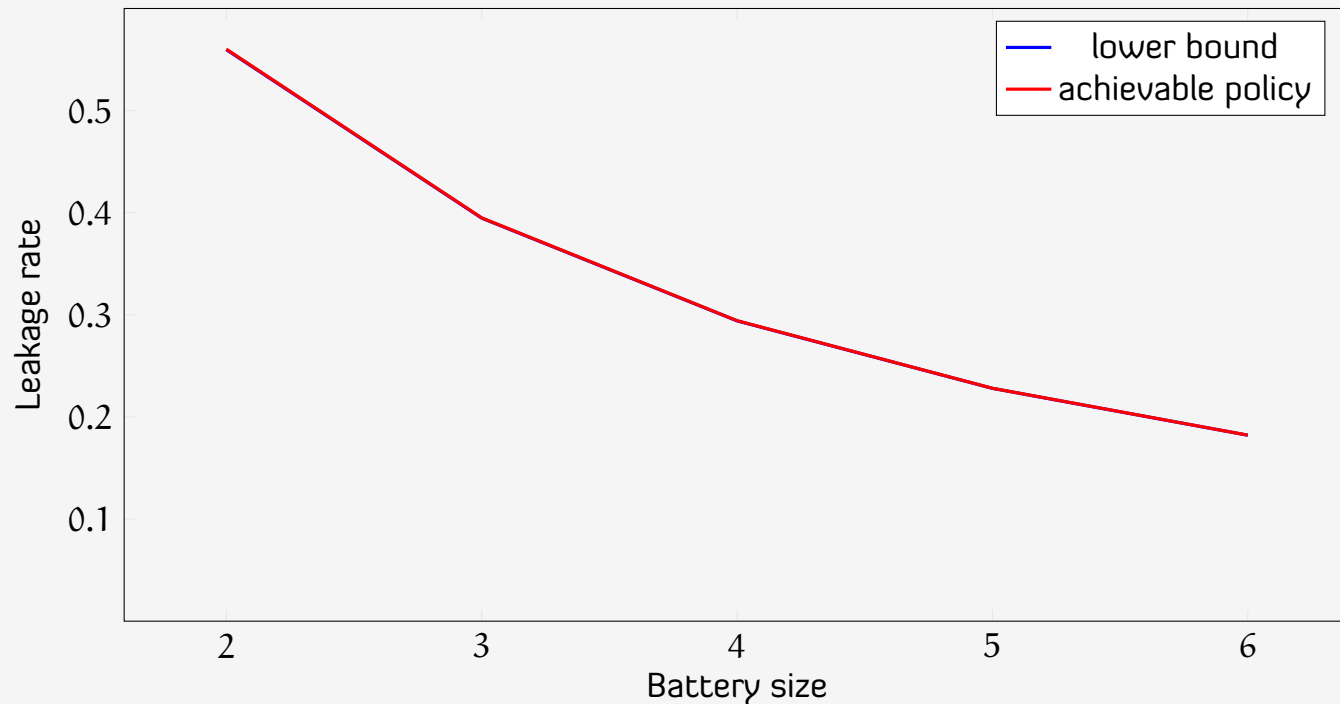
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Binary Model $\mathcal{X} = \mathcal{Y} = \{0, 1\}$. $Q_1 = [0.7 \ 0.3]$, $Q_2 = [0.3 \ 0.7]$.



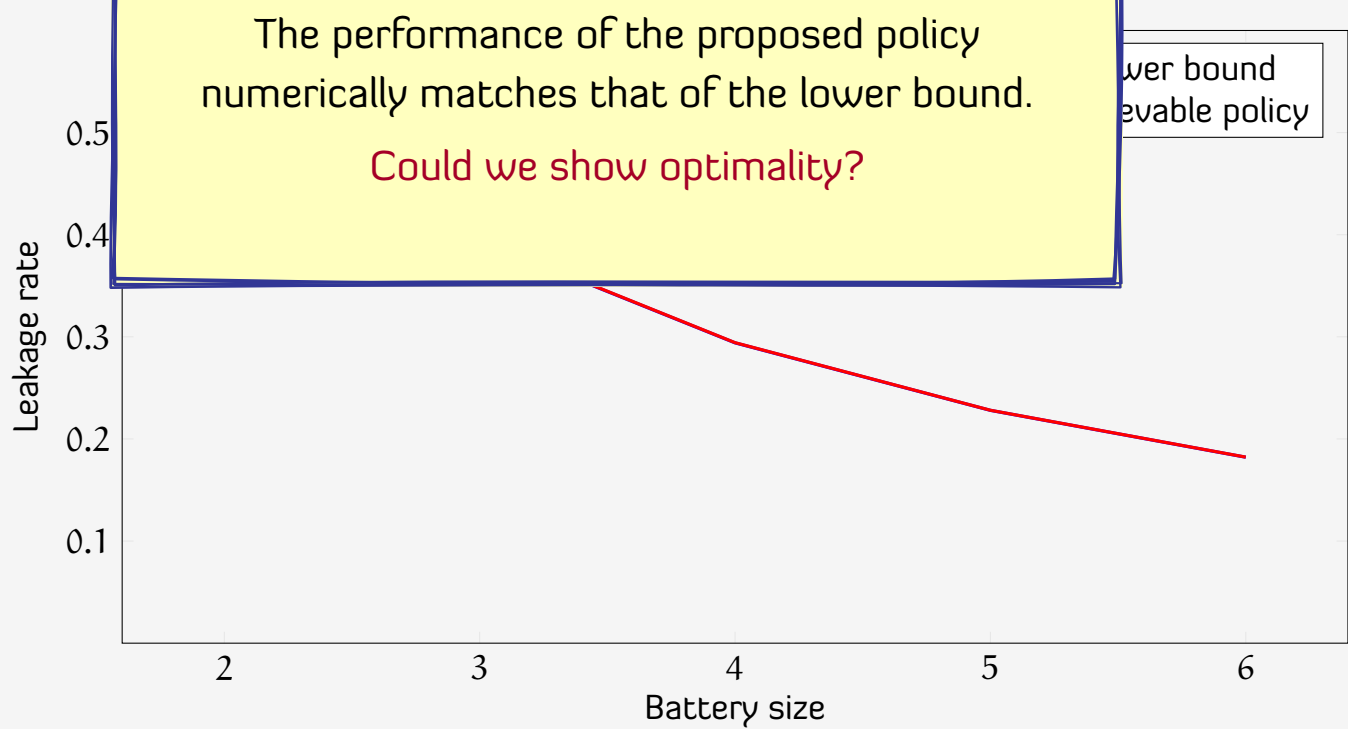
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Ternary Model $\mathcal{X} = \mathcal{Y} = \{0, 1, 2\}$. $Q_1 = [0.33 \ 0.33 \ 0.33]$, $Q_2 = [0.25 \ 0.5 \ 0.25]$.



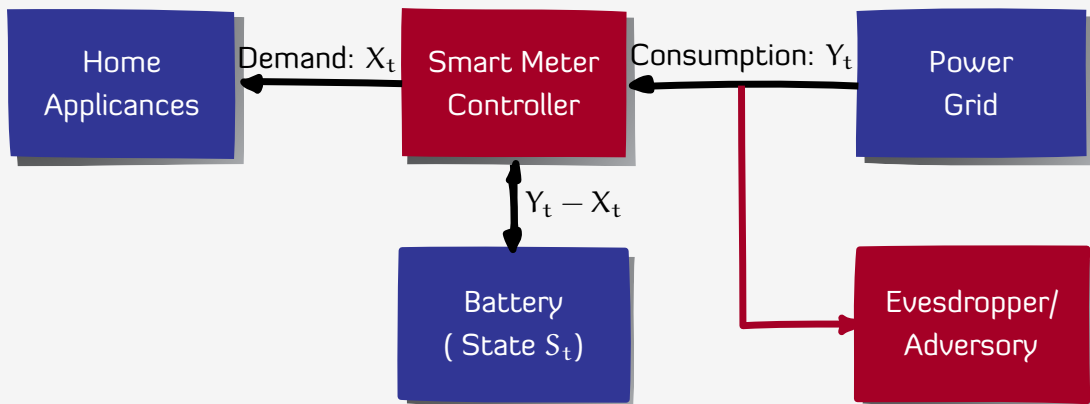
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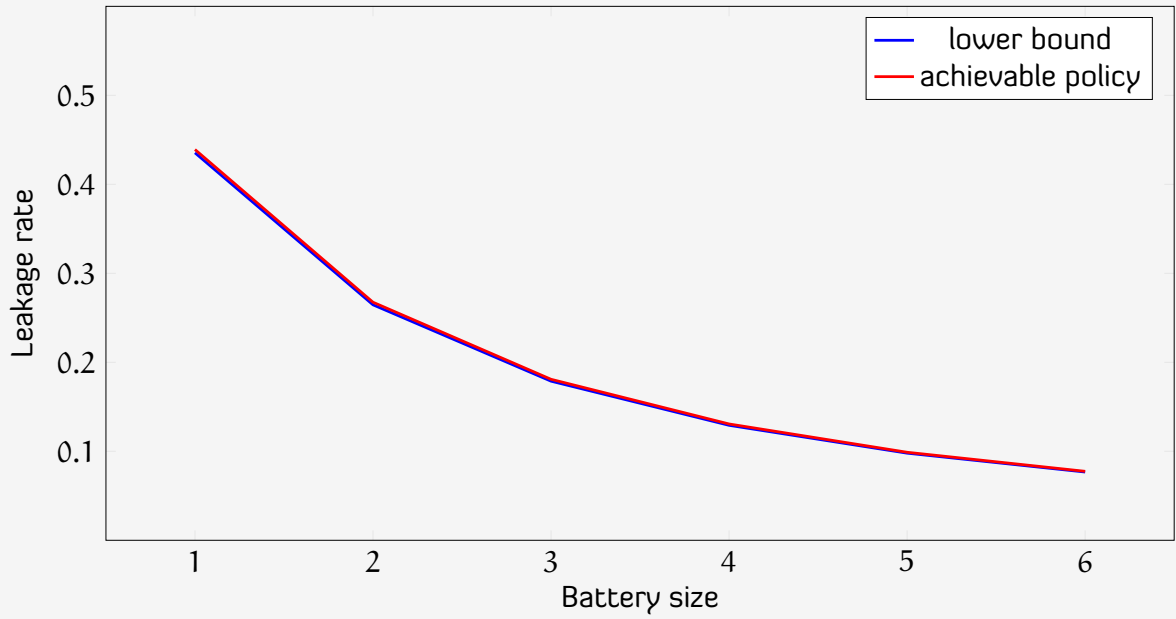
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